

Context-free Groups and Their Structure Trees

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Theorem

Let Γ be a connected, locally finite graph of finite tree-width and let a group G act on Γ with finitely many orbits and finite vertex stabilizers.

Then there is a tree T such that G acts on T with finitely many orbits and finite vertex stabilizers.

Corollary (Muller, Schupp, 1983)

A group is context-free if and only if it is finitely generated virtually free.

Virtually free \Rightarrow context-free: construct a pushdown automaton.

Context-free \Rightarrow virtually free:

- 1 G context-free \implies Cayley graph finite tree-width.
- 2 Theorem above implies that G acts on T with finitely many orbits and finite vertex stabilizers.
- 3 Bass-Serre implies that G is a fundamental group of a finite graph of finite groups.
- 4 Karrass, Pietrowski, and Solitar (1973) implies that G is virtually free.

context-free \Rightarrow virtually free (proof by Muller and Schupp):

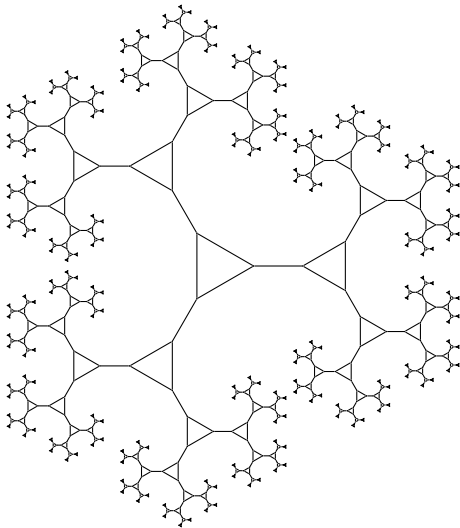
- 1 G context-free \iff
Cayley graph is quasi-isometric to a tree.
- 2 Cayley graphs which are quasi-isometric to a tree have more than one end.
- 3 Apply Stallings' Structure Theorem (1971).
- 4 Use the result by Dunwoody (1985) that finitely presented groups are accessible. (This piece was still missing 1983.)
- 5 Apply the theorem by Karrass, Pietrowski, and Solitar (1973) to see that the group is virtually free.

Definition

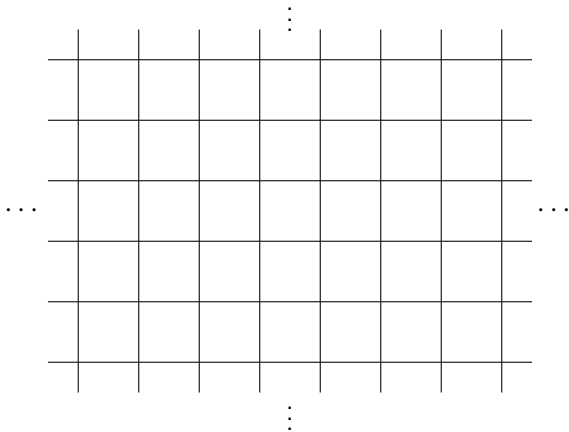
A graph Γ has finite tree-width if there is a tree $T = (V(T), E(T))$ and for every vertex $t \in V(T)$ a *bag* $X_t \subseteq V(\Gamma)$ such that

- Every node $v \in V(\Gamma)$ and every edge $uv \in E(\Gamma)$ is contained in some bag.
- If $v \in X_s \cap X_t$ for two nodes s, t of the tree, then v is contained in every bag of the unique geodesic in the tree from s to t .
- The size of the bags is bounded by some constant.

Modular group



The Cayley graph of $\mathrm{PSL}(2, \mathbb{Z}) \cong \mathbb{Z}/2\mathbb{Z} * \mathbb{Z}/3\mathbb{Z}$ has finite tree-width.

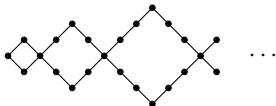


The Cayley graph of $\mathbb{Z} \times \mathbb{Z}$ does not have finite tree-width.

Finite tree-width vs. quasi-isometric to a tree

In general, both classes are incomparable:

- Infinite clique does not have finite tree-width, but is quasi-isometric to a point.
- The following graph has finite tree-width, but is not quasi-isometric to a tree.



However, for Cayley graphs are equivalent:

- quasi-isometric to a tree,
- finite tree-width.

Starting point:

Γ = connected, locally finite graph of finite tree-width

G = group acting on Γ with finitely many orbits and finite vertex stabilizers

For $C \subseteq V(\Gamma)$ let $\delta C = \{ uv \in E(\Gamma) \mid u \in C, v \in \overline{C} \}$ be the *boundary*.

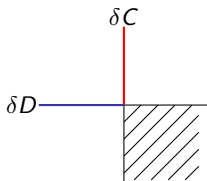
Definition

A *cut* is a subset $C \subseteq V(\Gamma)$ such that δC is finite.

Definition

A *tree set* is a set of cuts \mathcal{C} such that

- $C \in \mathcal{C} \Rightarrow \overline{C} \in \mathcal{C}$,
- cuts in \mathcal{C} are pairwise nested, i.e., for $C, D \in \mathcal{C}$ either $C \subseteq D$ or $C \subseteq \overline{D}$ or $\overline{C} \subseteq D$ or $\overline{C} \subseteq \overline{D}$,
- the partial order (\mathcal{C}, \subseteq) is discrete.



The aim is to construct a tree set \mathcal{C} .

Why tree sets?

A cut C of tree set defines an undirected edge $\{[C], [\bar{C}]\}$ in a tree for the following equivalence relation.

Definition

For $C, D \in \mathcal{C}$ the relation $C \sim D$ is defined as follows:

Either $C = D$,

or $\bar{C} \subsetneq D$ and there is no $E \in \mathcal{C}$ with $\bar{C} \subsetneq E \subsetneq D$.

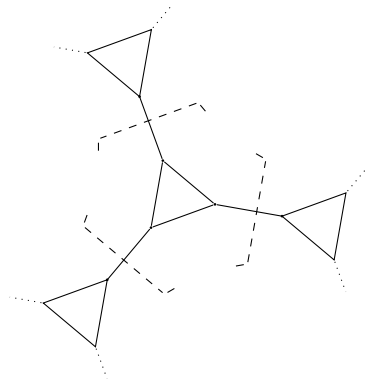
Proposition (Dunwoody, 1979)

The graph $T(\mathcal{C})$ is a tree, where

Vertices: $V(T(\mathcal{C})) = \{[C] \mid C \in \mathcal{C}\}$,

Edges: $E(T(\mathcal{C})) = \{\{[C], [\bar{C}]\} \mid C \in \mathcal{C}\}$.

Vertices in the structure tree

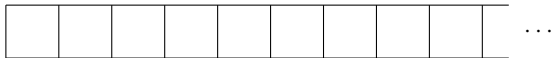


Three cuts in one equivalence class = one vertex in $T(\mathcal{C})$.

Facts about Γ

- There exists some k such that every bi-infinite geodesic can be split into two infinite pieces by some k -cut., i.e., $|\delta(C)| \leq k$.
 - Every bi-infinite geodesic defines two different ends.
 - Every pair of ends can be separated by a k -cut.
- If Γ is infinite, then there exists some bi-infinite geodesic.

We need $|\text{Aut}(\Gamma) \backslash \Gamma| < \infty$: There are graphs with arbitrarily long geodesics, bi-infinite simple paths, but without any bi-infinite geodesic:

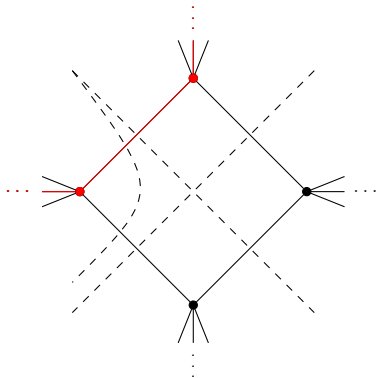


Here: $\text{Aut}(\Gamma) = \mathbb{Z}/2\mathbb{Z}$ and $\text{Aut}(\Gamma) \backslash \Gamma = \mathbb{N}$.

Minimal cuts

Minimal cuts = cuts which are minimal splitting an infinite geodesic.

Minimal cuts still might not be nested:



A cut C is **optimal**, if it cuts a bi-infinite geodesic α with $|\delta C|$ minimal and with a minimal number of not nested cuts.

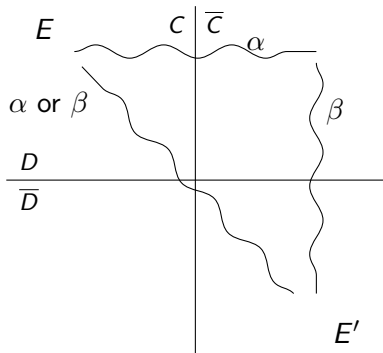
Theorem

- *Every bi-infinite geodesic is split by an optimal cut.*
- *Optimal cuts are pairwise nested.*

Corollary

The optimal cuts form a tree set and the action of G on Γ induces an action of G on \mathcal{C}_{opt} .

Optimal Cuts

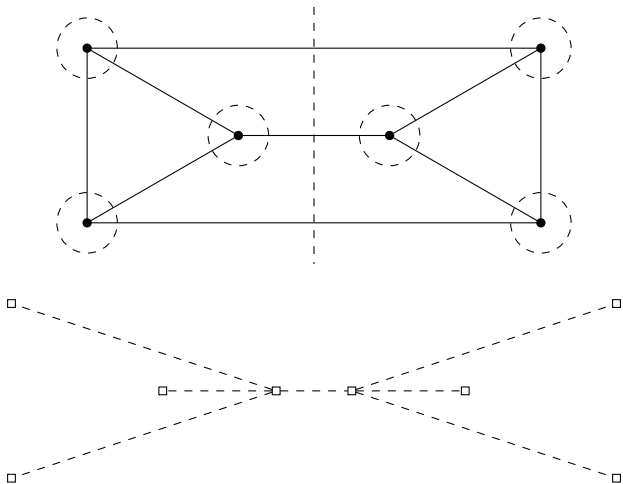


$$\delta E \cup \delta E' \subseteq \delta C \cup \delta D$$

$$\delta E \cap \delta E' \subseteq \delta C \cap \delta D$$

$$|\delta E| + |\delta E'| \leq |\delta C| + |\delta D|$$

Example



Theorem

The group G acts on the tree $T(\mathcal{C}_{\text{opt}})$ with finitely many orbits and finite vertex stabilizers.

Proof.

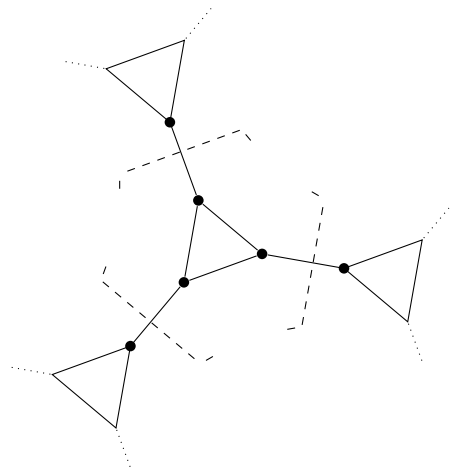
Construct a tree decomposition of Γ assigning to each $[C] \in V(T(\mathcal{C}_{\text{opt}}))$ a block $B[C]$ with

$$B[C] = \bigcap_{D \sim C} N^\lambda(D).$$

- 1 Blocks are connected.
- 2 The stabilizer $G_{[C]}$ acts with finitely many orbits on $B[C]$.
- 3 There is no cut in $B[C]$ which splits some bi-infinite geodesic.



Vertices in the structure tree and blocks



A block assigned to an equivalence class consisting of three cuts.

Concluding remarks

- Proof based on “Cutting up graphs revisited – a short proof of Stallings’ structure theorem” by Krön (2010).
- Direct, one-step construction of the structure tree.
- Muller-Schupp-Theorem as corollary.
- Solution of the isomorphism problem for context-free groups in elementary time if the minimal cuts can be computed in elementary time. (Known: primitive recursive (Sénizergues, 1993))

Thank you!