Computing automorphism groups and testing groups for isomorphism

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Questions, Algorithms, and Computations in Abstract Group Theory, Braunschweig, May 2013 1 Search problems in computational group theory

- Automorphism groups of finite *p*-groups
- 3 Automorphism groups of general finite groups
- 4 An alternative approach using automorphisms of p-groups
- **5** Representing automorphism groups

6 Bibliography

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- Such problems often come in pairs, one of which is to compute a certain subgroup and the other is to find a representative of a coset of the subgroup, which may or may not exist.
- Algorithms for the two problems are typically very similar, so they can be considered (and implemented) together.

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  - b) Test two elements of G for conjugacy and find a conjugating element if it exists.

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### **3** For $G \leq \text{Sym}(X)$ :

- a) Find the stabilizer of a subset of X;
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$$G \leq \operatorname{GL}_n(\mathbb{F}_q)$$
 acting on  $V = \mathbb{F}_q^n$ :

- a) Find the stabilizer of a subspace W of V;
- b) For two subspaces W, X of V, test for existence of  $g \in G$  with  $W^g = X$  and find g if it exists.

# Automorphism groups and isomorphism testing

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We find a generating set S of G with  $|S| \leq \log_2 n$ . A homomorphism  $G \to G$  is determined by the images of the elements of S, so we just try all  $n^{|S|}$  such images, and test whether they define automorphisms of G.

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For primes p, G. Higman showed how to construct about  $p^{2n^3/27}$  non-isomorphic groups of order  $p^n$ . These are special p-groups with about 2n/3 generators. It is unlikely that two such groups can be tested for isomorphism any faster than this.

So all that we can do is to look for algorithms that perform well in practice on small or interesting examples. So all that we can do is to look for algorithms that perform well in practice on small or interesting examples.

From our naive analysis above, we would expect this to be substantially easier for groups with small numbers of generators, and this turns out to be the case: the minimal generator number is the most significant factor influencing performance of implemented methods. So all that we can do is to look for algorithms that perform well in practice on small or interesting examples.

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For the remainder of the talk, everything said about computing AutG applies also to the group isomorphism testing problem.

(In fact group isomorphism testing is one of the facilities that is used most frequently by typical users of computer algebra packages, such as **GAP** and **Magma**.)

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The lower p-central series of G is defined by

 $P_0(G) := G; \quad P_i(G) := [P_{i-1}(G), G]P_{i-1}(G)^p \ (i > 0).$ 

We work downwards through the quotients  $G/P_i(G)$ , computing Aut $(G/P_i(G))$  for i = 1, 2, 3, ...

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The critical step in going from *i* to i + 1 is the calculation of the stabilizer of a subspaces in the action of  $Aut(G/P_i(G))$  on the *p*-multiplicator of  $G/P_i(G)$ , which can be regarded as a vector space over  $\mathbb{F}_p$ .

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- **1** Compute the solvable radical  $L := O\infty(G)$  of G.
- 2 Solve the problem in G/L using known properties of the nonabelian simple direct factors of Soc(G/L).
- **3** Solve the problem in G using linear algebra to lift the solution through the elementary abelian layers of L.

For the automorphism group computation, we first find a series

$$G \geq L = N_1 > N_2 > \cdots N_r = 1$$

of characteristic subgroups of G, where  $L = N_1 = O\infty(G)$ , and each  $N_i/N_{i+1}$  is elementary abelian.

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This involves **black box recognition** algorithms for the finite simple groups.

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Given an elementary abelian *p*-subgroup *N* of *G*, for which  $\overline{A} := \operatorname{Aut}(G/N)$  is known, compute  $A := \operatorname{Aut}G$ .

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We have a series  $1 \leq C \leq B \leq A$  of normal subgroups of A defined by

 $B := \{ \alpha \in A \mid \alpha_{G/N} = 1 \}; \qquad C := \{ \beta \in B \mid \beta_N = 1 \}.$ 

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The subgroups C and B do not depend on  $\overline{A}$ , and are typically comparatively straightforward to compute:

 $C = H^1(G/N, N)$  and  $B/C = \operatorname{Aut} N$  as  $\mathbb{F}_p G/N$ -module.

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The most difficult problem is computing A/B, which is a search problem, where we need to determine which elements of  $\overline{A}$  lift to A.

The special methods for p-groups, where we reduce to a subspace stabilizer computation, are not available here.

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On some types of examples, such as iterated wreath products of  $S_3$  or  $S_4$ , it is no good at all, because computing Aut*P* for the Sylow subgroups is slower than computing Aut*G* with existing methods,

Let A := AutG. For simplicity, assume that G is solvable.

#### Lemma

If  $O_p(G)$  and  $O_q(G)$  are nontrivial for distinct primes p, q, then  $G \leq G/O_q(G) \times G/O_p(G)$  and  $\operatorname{Aut} G \leq \operatorname{Aut}(G/O_q(G)) \times \operatorname{Aut}(G/O_p(G))$ . Let A := AutG. For simplicity, assume that G is solvable.

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So we assume that there is a unique prime p with  $1 \neq K := O_p(G)$ .

Let G = PQ with  $P \in Syl_p(G)$  and Q a complement of P in G. Then:

#### Lemma

We have 
$$A = A_{P,Q} \operatorname{Inn} G$$
, where  $A_{P,Q} = \{ \alpha \in A \mid P^{\alpha} = P, Q^{\alpha} = Q \}$ .

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## Groups with a large Sylow subgroup (ctd)

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The case when  $P \trianglelefteq G$  (i.e. K = P) is easy.

### Proposition

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### More generally, we have

### Proposition

 $A_{P,Q}$  is isomorphic to a subgroup of

$$B := \{ \alpha \in \operatorname{Aut} P \mid K^{\alpha} = K, \ N_{P}(Q)^{\alpha} = N_{P}(Q), \ \alpha|_{K} \in N_{\operatorname{Aut} K}(\overline{Q}) \}.$$

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### a nice representation of $\mathsf{Aut}\mathsf{P}$

We use a permutation representation if one can be found of reasonably small degree.

In general, the *p*-group automorphism algorithm calculates a normal *p*-subgroup *S* of Aut*P* and a representation of (AutP)/S as a subgroup of  $GL_d(p)$ , where *d* is size of a minimal generating set of *P*.

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Otherwise we can treat Aut*P* as a **hybrid group**, which we define to be a finite group *G* with a solvable normal subgroup *S*, defined by a PC-presentation, together with a nice representation of G/S.

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Implementations of algorithms for such groups are useful in other contexts, such as computations in large matrix group with nontrivial solvable radical.

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